

Signal detection

Let $r[n]$ be a noisy signal that is either:

$$H_0: R[n] = W[n]$$

$$H_1: R[n] = s[n] + W[n]$$

where $s[n]$ is the signal that we are trying to detect, and $W[n]$ is an i.i.d. zero-mean Gaussian process with variance σ^2 .

The [maximum a posteriori rule](#) can be written as:

$$\frac{f(r[0], r[1], \dots, r[L-1] | H_1)}{f(r[0], r[1], \dots, r[L-1] | H_0)} \overbrace{\phantom{\frac{f(r[0], r[1], \dots, r[L-1] | H_1)}}}^{\text{'H}_1\text{'}} \underbrace{\phantom{\frac{f(r[0], r[1], \dots, r[L-1] | H_0)}}}_{\text{'H}_0\text{'}} \frac{p_0}{p_1}$$

Given that $W[n]$ is Gaussian, this can be rewritten as:

$$\frac{\prod_{n=0}^{L-1} \left(\frac{1}{\sigma \sqrt{2\pi}} e^{-\frac{(r[n] - s[n])^2}{2\sigma^2}} \right)}{\prod_{n=0}^{L-1} \left(\frac{1}{\sigma \sqrt{2\pi}} e^{-\frac{(r[n])^2}{2\sigma^2}} \right)} \overbrace{\phantom{\frac{\prod_{n=0}^{L-1} \left(\frac{1}{\sigma \sqrt{2\pi}} e^{-\frac{(r[n] - s[n])^2}{2\sigma^2}} \right)}}}^{\text{'H}_1\text{'}} \underbrace{\phantom{\frac{\prod_{n=0}^{L-1} \left(\frac{1}{\sigma \sqrt{2\pi}} e^{-\frac{(r[n])^2}{2\sigma^2}} \right)}}}_{\text{'H}_0\text{'}} \frac{p_0}{p_1}$$

After some simplifications, we get:

$$g = \sum_{n=0}^{L-1} r[n] s[n] \overbrace{\phantom{\sum_{n=0}^{L-1} r[n] s[n]}}^{\text{'H}_1\text{'}} \underbrace{\phantom{\sum_{n=0}^{L-1} r[n] s[n]}}_{\text{'H}_0\text{'}} \sigma^2 \ln \eta + \frac{\text{varepsilon}}{2} = \gamma$$

where $\eta = \frac{p_0}{p_1}$ and $\text{varepsilon} = \sum_{n=0}^{L-1} s^2[n]$ (Energy)

Let G be the random variable of which g is a realized value. Similarly, $R[n]$ is the random process of which $r[n]$ is a realized instance. Then,

$$G = \sum_{n=0}^{L-1} R[n] s[n]$$

The distributions of G are:

$$H_0: G \sim \mathcal{N}(0, \sigma^2 \text{varepsilon}) \quad H_1: G \sim \mathcal{N}(\text{varepsilon}, \sigma^2 \text{varepsilon})$$

Note that the variance is the same in both cases.

Matched filter

A matched filter is used to detect a known signal $s[n]$ in white Gaussian noise.

The filter is the time reverse of the signal:

$$h[n] = s[-n]$$

In the frequency domain:

$$H(e^{j\Omega}) = S(e^{-j\Omega}) = |S(e^{j\Omega})| e^{-j\angle S(e^{j\Omega})}$$

Consider filtering a noisy signal $r[n]$ with the matched filter $h[n]$:

$$g[n] = (h \ast r)[n] = (\overleftarrow{s} \ast r)[n]$$

In the ideal case where $r[n] = s[n]$, the output is deterministic autocorrelation:

$$g[n] = (h \ast r)[n] = (s \ast \overleftarrow{s})[n] = \bar{R}_{ss}[n]$$

The matched filter maximizes the spread between the H_0 and H_1 cases.

Compare the $g[n]$ with the threshold $\gamma = \sigma_W^2 \ln \frac{p_0}{p_1} + \frac{\epsilon}{2}$. If $g[n] > \gamma$, declare H_1 . Otherwise, declare H_0 .

Probability of error

The conditional probability of false alarm is:

$$P_{FA} = Q\left(\frac{\gamma}{\sigma \sqrt{\epsilon}}\right)$$

$$P_M = 1 - Q\left(\frac{\gamma - \epsilon}{\sigma \sqrt{\epsilon}}\right)$$

Total probability is:

$$P_e = p_0 P_{FA} + p_1 P_M$$

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